Setting

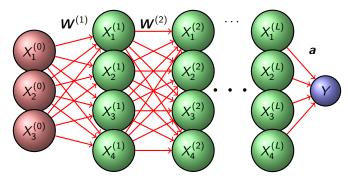
F. Camilli, **D. Tieplova**, J. Barbier, and E. Bergamin

Log-gases in Caeli Australi, MATRIX Institute, Creswick, Australia 4-15 Aug 2025

Deep Neural Network

$$\mathbf{X}^{(0)} \sim \mathcal{N}(0, d_0^{-1} \mathbb{I}_{d_0})$$

Setting •00000



$$oldsymbol{\mathcal{X}}^{(\ell)} = d_{\ell-1}^{-1/2} arphi \Big(oldsymbol{W}^{(\ell)} oldsymbol{\mathcal{X}}^{(\ell-1)} \Big) \, \in \mathbb{R}^{d_\ell}$$

$$Y = f\left(\mathbf{a}^{\mathsf{T}}\mathbf{X}^{(L)}\right)$$

$$\varphi$$
 – activation function

f -readout function.

Supervised learning: Starting from a *training set* $\mathcal{D}_n^{(L)} = \{(\boldsymbol{X}_{\mu}^{(0)}, Y_{\mu})_{\mu=1}^n\}$, we adjust the weights $\boldsymbol{a}, \boldsymbol{W}^{(1)}, \dots, \boldsymbol{W}^{(L)}$ s.t.

$$Y_{\mu} pprox f\left(oldsymbol{a}^{\mathsf{T}} arphi\left(oldsymbol{W}^{(L)} arphi\left(\dots arphi\left(oldsymbol{W}^{(1)} oldsymbol{X}_{\mu}^{(0)}
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Main Goa

Setting

Produce the smallest possible generalization error:

$$\mathcal{E} = \left[Y_{\text{new}} - f \left(\boldsymbol{a}^{\mathsf{T}} \boldsymbol{X}_{\text{new}}^{(L)} \right) \right]^{2}$$

for a new couple $(X_{\text{new}}, Y_{\text{new}})$

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The training set is generated by a *L*-layer **teacher network** with matching architecture:

$$egin{align} oldsymbol{Y}_{\mu} &= f\Big(oldsymbol{a}^{*\intercal}oldsymbol{X}_{\mu}^{(L)}\Big) + \sqrt{\Delta} Z_{\mu} \,, \quad orall \mu \leq n \ oldsymbol{X}_{\mu}^{(\ell)} &= arphi\Big(oldsymbol{W}^{(\ell)*}oldsymbol{X}_{\mu}^{(\ell-1)}\Big) \,, \quad \ell = 1, \ldots, L \,, \end{align}$$

for $\Delta > 0$, $Z_{\mu} \stackrel{\text{iid}}{\sim} \mathcal{N}(0,1)$. Prior on the weights $(\theta^{(L)*})$: $a_i^*, W_{ij}^{(\ell)*} \stackrel{\text{iid}}{\sim} \mathcal{N}(0,1)$. Same as

$$Y_{\mu} \sim P_{\mathrm{out}}\Big(\cdot \mid \boldsymbol{a}^{*\intercal} \boldsymbol{X}_{\mu}^{(L)}\Big)$$

with

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$$P_{\mathrm{out}}(y \mid x) = \frac{1}{\sqrt{2\pi\Delta}} \exp\left(-\frac{1}{2\Delta} (f(x) - y)^2\right)$$

Bayes-optimal student

Definition (informal)

A student network is Bayes-optimal if it is completely aware of the generative model

$$Y_{\mu} = f\left(\boldsymbol{a}^{*\intercal}\boldsymbol{X}_{\mu}^{(L)}\right) + \sqrt{\Delta}Z_{\mu}, \quad \forall \mu \leq n,$$

and it matches the teacher's architecture. In other words: apart from the true weights, it knows everything there is to know.

A Bayes-optimal student has access to the Bayes-posterior:

$$dP(\boldsymbol{\theta}^{(L)} \mid \mathcal{D}_n^{(L)}) = \frac{1}{\mathcal{Z}(\mathcal{D}_n^{(L)})} \prod_{\mu=1}^n P_{\text{out}} \Big(Y_\mu \mid \boldsymbol{a}^\intercal \boldsymbol{x}_\mu^{(L)} \Big) D\boldsymbol{\theta}^{(L)}$$

where $D\theta^{(L)} = DaDW^{(1)} \dots W^{(L)}$ is the Gaussian prior on the weights.

Proposition (informal)

Setting

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A Bayes-optimal student NN achieves the lowest expected generalization error

$$\mathbb{E}\mathcal{E} := \mathbb{E}ig(Y_{ ext{new}} - \hat{Y}(\mathcal{D}_n^{(L)}, oldsymbol{X}_{ ext{new}}^{(0)})ig)^2$$

that is yielded by the BO predictor

$$\begin{split} \hat{Y}_{\mathrm{Bayes}}(\mathcal{D}_{n}^{(L)}, \boldsymbol{X}_{\mathrm{new}}^{(0)}) &= \mathbb{E}[Y_{\mathrm{new}} \mid \mathcal{D}_{n}^{(L)}, \boldsymbol{X}_{\mathrm{new}}^{(0)}] \\ &= \int dY \, Y \, P_{\mathrm{out}}\Big(Y \mid \boldsymbol{a}^{\mathsf{T}} \boldsymbol{x}_{\mathrm{new}}^{(L)}\Big) dP(\boldsymbol{\theta}^{(L)} \mid \mathcal{D}_{n}^{(L)}) \,. \end{split}$$

Main information theoretic quantities

Partition function or evidence:

$$\mathcal{Z}(\mathcal{D}_n^{(L)}) = \int \prod_{\mu=1}^n P_{\text{out}}\Big(Y_\mu \mid \boldsymbol{a}^\mathsf{T} \boldsymbol{x}_\mu^{(L)}\Big) D\boldsymbol{\theta}^{(L)}$$

Main result

- Free entropy: $\bar{f}_n^{(L)} = \frac{1}{n} \mathbb{E} \log \mathcal{Z}(\mathcal{D}_n^{(L)})$
- Mutual Information per data point:

$$\begin{split} \frac{I_n^{(L)}(\boldsymbol{\theta}^{(L)*}; \mathcal{D}_n^{(L)})}{n} &= \frac{H(\mathcal{D}_n^{(L)})}{n} - \frac{H(\mathcal{D}_n^{(L)} \mid \boldsymbol{\theta}^{(L)*})}{n} \\ &= -\bar{f}_n^{(L)} + \mathbb{E}\log P_{\mathrm{out}}\Big(Y_1 \mid \boldsymbol{a}^{*\mathsf{T}}\boldsymbol{X}_1^{(L)}\Big) \end{split}$$

Main information theoretic quantities

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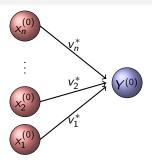
$$\mathcal{Z}(\mathcal{D}_n^{(L)}) = \int \prod_{\mu=1}^n P_{\text{out}}\Big(Y_\mu \mid \boldsymbol{a}^\mathsf{T} \boldsymbol{x}_\mu^{(L)}\Big) D\boldsymbol{\theta}^{(L)}$$

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A simpler ancestor: the GLM



The teacher Generalized Linear Model:

$$Y_{\mu}^{(0)} = f \left(\rho \mathbf{v}^{*\mathsf{T}} \mathbf{X}_{\mu}^{(0)} + \sqrt{\epsilon} \xi_{\mu}^{*} \right) + \sqrt{\Delta} Z_{\mu} \,,$$

or
$$Y_{\mu}^{(0)} \sim P_{\mathrm{out}} \Big(\cdot \mid \rho \mathbf{v}^{*\mathsf{T}} \mathbf{X}_{\mu}^{(0)} + \sqrt{\epsilon} \xi_{\mu}^{*} \Big)$$

with $v_i^*, \xi_\mu^* \stackrel{\text{\tiny iid}}{\sim} \mathcal{N}(0,1)$, $\rho, \epsilon \geq 0$.

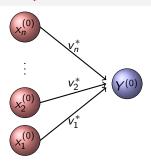
Free entropy

$$\bar{f}_n^{(0)} = \frac{1}{n} \mathbb{E} \log \int \prod_{\mu=1}^n P_{\text{out}} \left(Y_{\mu}^{(0)} \mid \rho \mathbf{v}^{\mathsf{T}} \mathbf{X}_{\mu}^{(0)} + \sqrt{\epsilon} \xi_{\mu} \right) D \mathbf{v} D \xi$$

Mutual information

$$\frac{1}{n} I_n^{(0)}(\mathbf{v}^*, \boldsymbol{\xi}^*; \mathcal{D}_n^{(0)}) = -\bar{f}_n^{(0)} + \mathbb{E} \log P_{\text{out}} \left(Y_1^{(0)} \mid \rho \mathbf{v}^{*\mathsf{T}} \mathbf{X}_1^{(0)} + \sqrt{\epsilon} \xi_1^* \right)$$

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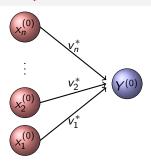
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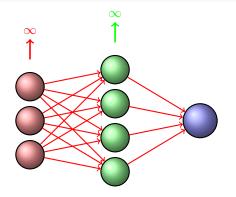
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Recent conjectures



Linear scalings

$$n, d_L, \ldots, d_0 \to \infty, \quad \frac{n}{d_\ell} = O(1)$$

- [Li-Sompolinsky-2021] studied full training for linear networks;
- [Ariosto-Pacelli-Pastore-Ginelli-Gherardi-Rotondo-2022] conjectures a formula for the ERM generalization error;
- [Cui-Krzakala-Zdeborová-2023] builds on a Gaussian Equivalence Principle to compute the Bayes-optimal limits as we do

Gaussian Equivalence Principles

GEP (informal)

It amounts to the following replacement:

$$\varphi\left(\mathbf{W}^{*}\mathbf{X}_{\mu}\right)pprox
ho\mathbf{W}^{*}\mathbf{X}_{\mu}+\sqrt{\epsilon}\xi_{\mu}^{*}$$

with ξ_u^* an independent standard Gaussian noise and

$$\rho = \mathbb{E}_{\mathcal{N}(0,1)} \varphi', \quad \epsilon = \mathbb{E}_{\mathcal{N}(0,1)} \varphi^2 - (\mathbb{E}_{\mathcal{N}(0,1)} \varphi')^2$$

In our setting, it is not clear to what extent this is applicable!

Setting

In the context of random kernel matrices $\Phi = \varphi^{\mathsf{T}}(\mathbf{W}^* \mathbf{X}) \varphi(\mathbf{W}^* \mathbf{X})$, also known as Conjugate Kernel.

- [Louart-Liao-Couillet-2017] found deterministic equivalent of the resolvent of Φ has similar behavior with sample covariance models
- [Pennington-Worah-2017] spectral distribution of Φ
- [Fan-Wang-2020] spectral distribution for multilayer conjugate kernel

One layer reduction

- $\varphi, f \in C^2(\mathbb{R})$ are odd and with bounded first and second derivatives.
- $\sigma_0 = 1$, $\sigma_\ell = \mathbb{E}\varphi^2(Z\sqrt{\sigma_{\ell-1}})$, $\rho_\ell = \mathbb{E}\varphi'(Z\sqrt{\sigma_{\ell-1}})$, $\epsilon_\ell = \sigma_\ell \sigma_{\ell-1}\rho_\ell^2$, where Z is a standard Gaussian.

$$\left|\frac{1}{n}I_n^{(L)} - \frac{1}{n}I_n^{(L-1)}\right| = O\left(\left(1 + \sqrt{\frac{n}{d_{min}}} + \frac{n}{d_{min}}\right)\frac{1}{\sqrt{d_{min}}}\right),$$

where responses for L-1-layer NN are drawn as

$$Y_{\mu}^{(L-1)} \sim P_{out} \Big(\cdot \mid \textcolor{red}{\rho_L} \mathbf{a}^{*\intercal} \mathbf{X}_{\mu}^{(L-1)} + \textcolor{red}{\sqrt{\epsilon_L}} \boldsymbol{\xi}_{\mu}^* \Big) \,.$$

Mutual information equivalence

Under the same assumptions, the following holds true:

$$\left|\frac{1}{n}I_n^{(L)}-\frac{1}{n}I_n^{(0)}\right|=O\Big(\Big(1+\sqrt{\frac{n}{d_{min}}+\frac{n}{d_{min}}}\Big)\frac{1}{\sqrt{d_{min}}}\Big)\,,$$

where $I_n^{(0)}$ is the mutual information associated with the data set $\mathcal{D}_n^{(0)}$ with responses

$$Y_{\mu}^{(0)} \sim P_{out} \Big(\cdot \mid \eta_0 \mathbf{a}^{*\mathsf{T}} \mathbf{X}_{\mu}^{(0)} + \sqrt{\gamma_0} \xi_{\mu}^* \Big)$$

and

$$\eta_0 = \prod_{i=1}^{L} \rho_i, \qquad \gamma_0 = \sum_{j=1}^{L} \epsilon_j \prod_{i=j+1}^{L} \rho_i^2.$$

Generalization Error

$$\widetilde{\lim} \equiv \lim_{n,d_\ell \to \infty} \text{ s.t. } \left(1 + \sqrt{\frac{n}{d_{\min}}} + \frac{n}{d_{\min}}\right) \frac{1}{\sqrt{d_{\min}}} \to 0 \ .$$

Corollary

Under the same hypothesis the following holds

$$\widetilde{\lim} |\mathcal{E}^{(L)} - \mathcal{E}^{(0)}| = 0,$$

where $\mathcal{E}^{(0)}$ is the GLM generalization error associated with $\frac{1}{n}I_n^{(0)}$.

Interpolation

Setting

The interpolation has to keep all the ingredients together:

$$\begin{split} S_{t\mu} &:= \sqrt{1-t} \Big[\mathbf{a}^{*\mathsf{T}} \varphi \Big(\mathbf{W}^{*(L)} \mathbf{X}_{\mu}^{(L-1)} \Big) \Big] + \sqrt{t} \Big[\rho_L \mathbf{v}^{*\mathsf{T}} \mathbf{X}_{\mu}^{(L-1)} + \sqrt{\epsilon_L} \zeta_{\mu}^{*(L)} \Big] \,, \\ s_{t\mu} &:= \sqrt{1-t} \Big[\mathbf{a}^{\mathsf{T}} \varphi \Big(\mathbf{W}^{(L)} \mathbf{x}_{\mu}^{(L-1)} \Big) \Big] + \sqrt{t} \Big[\rho_L \mathbf{v}^{\mathsf{T}} \mathbf{x}_{\mu}^{(L-1)} + \sqrt{\epsilon_L} \zeta_{\mu}^{(L)} \Big] \,, \end{split}$$

Interpolating dataset:

$$\mathcal{D}_t = \{ (Y_{t\mu}, \boldsymbol{X}_{\mu}^{(0)})_{\mu=1}^n \}, \quad Y_{t\mu} \sim P_{\text{out}} \big(\cdot \mid S_{t\mu} \big)$$

Interpolating free entropy:

$$\bar{f}_{n,t} = \frac{1}{n} \mathbb{E}_{(t)} \log \mathcal{Z}_t = \frac{1}{n} \mathbb{E}_{(t)} \log \int dP(\boldsymbol{\theta}^{(L)}) \mathbb{E}_{\mathbf{v}} \prod_{\mu=1}^{n} \mathbb{E}_{\zeta_{\mu}^{(L)}} P_{out} \Big(Y_{t\mu} \mid s_{t\mu} \Big).$$

Useful concentrations

Moment control

$$\mathbb{E}\Big|\|\mathbf{X}_{\mu}^{(\ell)}\|^2 - \sigma_{\ell}\Big|^k \le \frac{C_{k,\varphi}}{d_{\min}^{k/2}}.$$

Quasi-orthogonality propagation

$$\mathbb{E} \Big| \mathbf{X}_{\mu}^{(\ell)} \cdot \mathbf{X}_{
u}^{(\ell)} \Big|^k \leq rac{C_k}{d_{min}^{k/2}} \,.$$

Free entropy concentration

There exists a non-negative constant $C(f, \varphi)$ such that

$$\mathbb{V}\left(\frac{1}{n}\log \mathcal{Z}_t(\mathcal{D}_t)\right) \leq C(f,\varphi)\left(\frac{1}{n} + \frac{1}{d_{min}}\right).$$

Conclusions

- If $(1+\sqrt{\frac{n}{d_{\min}}}+\frac{n}{d_{\min}})\frac{1}{\sqrt{d_{\min}}}\to 0$ $(n\sim d_L\sim\ldots\sim d_0)$, training deep NN will give the same generalization error as if trained GLM.
- In order to escape this equivalence, deep neural networks must be analysed beyond the proportional regime (the number of samples n must grow much faster than d_{ℓ} , $n \sim \max\{d_{\ell}\}^2$).

Some References

Setting

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